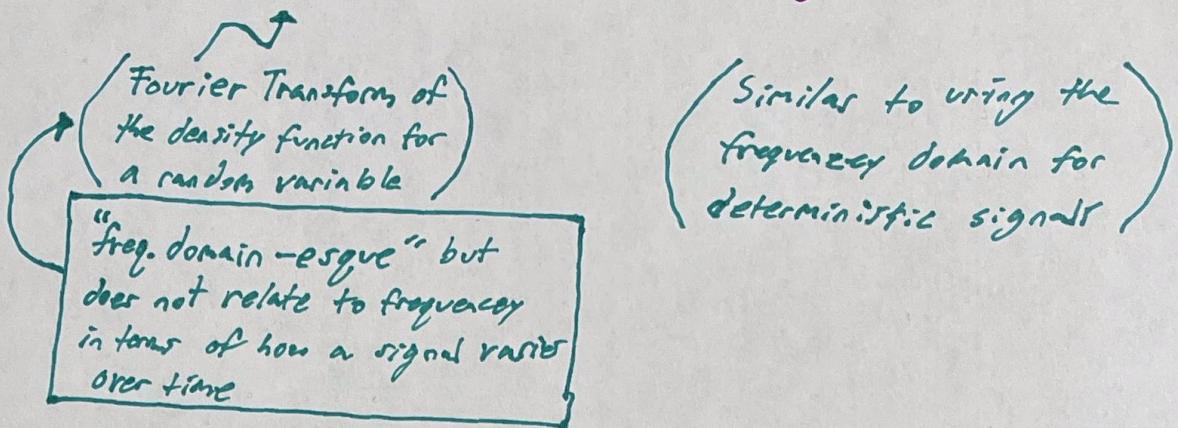


Frequency Spectrum of a WSS RP

04/15
(1 of 3)

- * Often useful to work w/ a RP in the frequency domain rather than the time domain
- * This differs from the characteristic & moment generating functions



- * Convolution may be avoided when finding $R_y(z) = (\tilde{h} * h * R_x)(z) \leftarrow_{\text{(System)}}^{(\text{LTI})}$
- * Filter design for a deterministic signal is typically easiest when working with the frequency domain representation (e.g., to filter noise, design a Low-Pass Filter & set cutoff frequency)
- * Noise in audio signals (e.g., white, pink, blue noise, etc.)

(defined in the freq. domain for audio signals)

How is the frequency spectrum defined for a Random Process?

⇒ Instead of finding the FT for each sample realization of the RP, use expectation to represent the frequency spectrum as a whole

(depends on the autocorrelation function)

* Define the frequency spectrum in terms of the autocorrelation function of the process

Power Spectral Density (PSD)

Def.: The PSD of a WSS RP $X(t)$ is

$$\boxed{S_x(\omega) = \int_{-\infty}^{\infty} R_x(\tau) e^{-i\omega\tau} d\tau \leftarrow (\text{FT of } R_x) \quad \omega \in \mathbb{R}}$$

(frequency variable, not sample space)

* Since $R_x(-\tau) = R_x(\tau)$, (" R_x is an even function in τ ")
 $S_x(\omega)$ is real-valued

$$* R_x(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_x(\omega) e^{i\omega\tau} d\omega \leftarrow (\text{Inverse FT})$$

* Since $R_x(\tau)$ is real, $S_x(\omega)$ is an even function of ω , $S_x(-\omega) = S_x(\omega)$, $\forall \omega \in \mathbb{R}$

Def.: The Cross Power Spectral Density of jointly WSS RP $X(t)$ & $Y(t)$ is

$$\boxed{S_{xy}(\omega) = \int_{-\infty}^{\infty} R_{xy}(\tau) e^{-i\omega\tau} d\tau}$$

* Recall that if $X(t) \xrightarrow[\text{(WSS)}]{h(t)} Y(t)$ then $R_y(\tau) = (h * h * R_x)(\tau)$

* Let the frequency response be the FT of the impulse response: $H(\omega) = \mathcal{F}\{h(t)\}$
 $\Rightarrow \mathcal{F}\{\tilde{h}(t)\} = \mathcal{F}\{h(-t)\} = H^*(\omega) \leftarrow (\text{Complex conjugate})$

* Even though $S_x(\omega)$ & $S_y(\omega)$ are real-valued, $H(t)$ may not be "even"
 (where $H(t) \neq H(-t)$, thus $H(\omega)$ would be complex)

$$\Rightarrow \boxed{S_y(\omega) = H^*(\omega) \cdot H(\omega) \cdot S_x(\omega) \quad \underbrace{\text{or } |H(\omega)|^2 S_x(\omega),}_{|H(\omega)|^2} \quad \forall \omega \in \mathbb{R}}$$

* NOTE: $R_{xy}(\tau) = (h * R_x)(\tau)$

Def.: A WSS RP is called White Noise if it is zero mean & the autocorrelation is a Dirac Delta function

$$\Rightarrow E[X(t)] = 0, \forall t \wedge R_X(\tau) = 0, \tau \neq 0$$

Thus, for white noise, $E[X(t_1)X(t_2)] = 0, t_1 \neq t_2$

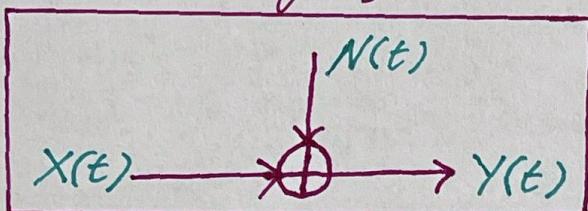
(for any 2 time instances that are non equal, the expectation of the product for these RVs is zero)

$\therefore X(t_1) \& X(t_2) \leftarrow \text{UNCORRELATED (if } t_1 \neq t_2\text{)}$
SINCE WHITE NOISE IS ZERO MEAN

* looking at 2 diff. time instances t_1 & t_2 , the RVs are uncorrelated

* The Gaussian model & White Noise model are often combined to model noise

Example: WSS Signal, $X(t)$

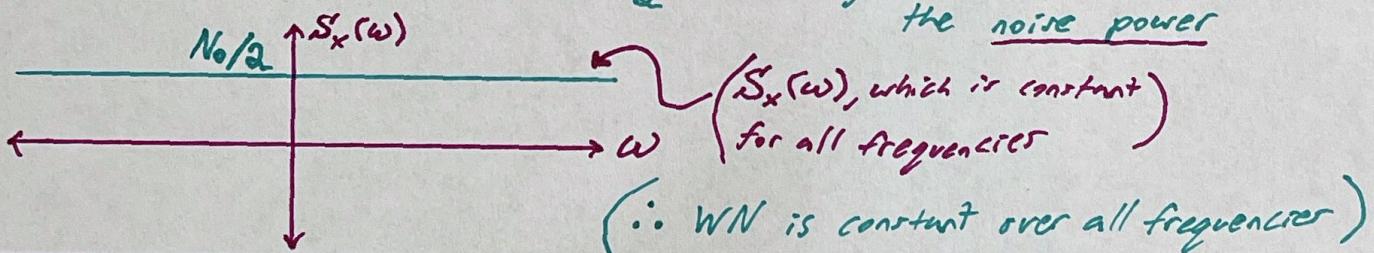


} (Often assumed that $N(t)$ is a Gaussian RP & is white noise)

\Rightarrow Additive White Gaussian Noise model (AWGN), where White Noise is an "idealization" - true enough

* What happens when you filter white noise?

* Let $X(t)$ be WN w/ $R_X(\tau) = \frac{N_0}{2} \delta(\tau)$, where N_0 is constant & represents the noise power



* Let $h(t) = e^{-t} u(t) \leftarrow$ (decaying exponential)

* What happens if WN is passed through filter $h(t)$?

$$M_y = M_x \int_{-\infty}^{\infty} h(t) dt = 0$$

$$\xrightarrow[\text{(inverse FT)}]{} R_y(\tau) = \frac{N_0}{4} e^{-|\tau|}, \tau \in \mathbb{R}$$

$$H(\omega) = \frac{1}{1+j\omega} \Rightarrow S_y(\omega) = |H(\omega)|^2 S_x(\omega) = \frac{N_0/2}{1+\omega^2}$$

